

# SANYO Semiconductors DATA SHEET

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# Monolithic Digital IC PWM Current Control Type Stepping Motor Driver

#### **Overview**

The LB1945H is a PWM current control type stepping motor driver.

### Feature

- PWM current control (external excitation)
- Load current digital selection (1-2, W1-2, and 2 phase excitation drives possible)
- Built-in upper/lower diode
- Simultaneous ON prevention function (feed-through current prevention)
- Built-in thermal shutdown circuit
- Built-in noise canceler

#### **Specifications** Absolute Maximum Ratings at $Ta = 25^{\circ}C$

|                              | •                   |                                |                         |      |
|------------------------------|---------------------|--------------------------------|-------------------------|------|
| Parameter                    | Symbol              | Conditions                     | Ratings                 | Unit |
| Maximum motor supply voltage | V <sub>BB</sub> max |                                | 30                      | V    |
| Output peak current          | I <sub>O</sub> peak | $t_W \le 20 \mu s$             | 1.0                     | А    |
| Output continuous current    | I <sub>O</sub> max  |                                | 0.8                     | А    |
| Logic supply voltage         | V <sub>CC</sub> max |                                | 6.0                     | V    |
| Logic input voltage range    | V <sub>IN</sub> max |                                | -0.3 to V <sub>CC</sub> | V    |
| Emitter output voltage       | V <sub>E</sub> max  |                                | 1.0                     | V    |
| Allowable power dissipation  | Pd max              | Mounted on a specified board * | 1.9                     | W    |
| Operating temperature        | Topr                |                                | -20 to +90              | °C   |
| Storage temperature          | Tstg                |                                | -55 to +150             | °C   |

\* Specified board: 114.3mm × 76.1mm × 1.6mm, glass epoxy board.

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## LB1945H

### Allowable Operating Ranges at $Ta = 25^{\circ}C$

| Parameter            | Symbol           | Conditions | Ratings      | Unit |
|----------------------|------------------|------------|--------------|------|
| Motor supply voltage | V <sub>BB</sub>  |            | 10 to 28     | V    |
| Logic supply voltage | V <sub>CC</sub>  |            | 4.75 to 5.25 | V    |
| Reference voltage    | V <sub>REF</sub> |            | 1.5 to 5.0   | V    |

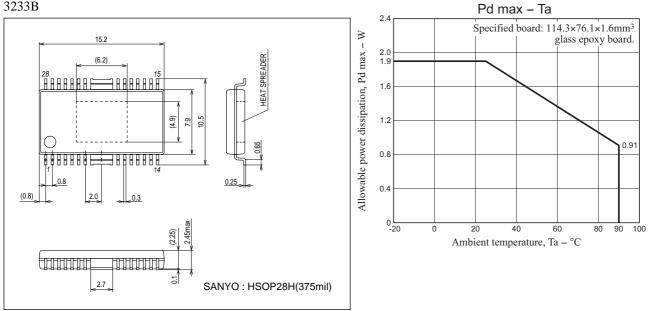
## **Electrical Characteristics** at Ta = 25°C, $V_{BB}$ = 24V, $V_{CC}$ = 5V, $V_{REF}$ = 5.0V

| Parameter                     | Symbol Conditions      | Conditions  | Ratings |     |      |      |
|-------------------------------|------------------------|---|---------|-----|------|------|
| Parameter                     | Symbol Conditions      |   | min     | typ | max  | Unit |
| Output Block                  |                        |   |         |     |      |      |
| Output stage supply current   | I <sub>BB</sub> ON     | I <sub>1</sub> = 0.8V, I <sub>2</sub> = 0.8V, ENABLE = 0.8V | 0.5     | 1.0 | 2.0  | mA   |
|                               | I <sub>BB</sub> OFF    | ENABLE = 3.2V   |         |     | 0.2  | mA   |
| Output saturation voltage     | V <sub>O</sub> sat1    | I <sub>O</sub> = +0.5A, sink                                |         | 0.3 | 0.5  | V    |
|                               | V <sub>O</sub> sat2    | I <sub>O</sub> = +0.8A, sink                                |         | 0.5 | 0.7  | V    |
|                               | V <sub>O</sub> sat3    | I <sub>O</sub> = -0.5A, source                              |         | 1.6 | 1.8  | V    |
|                               | V <sub>O</sub> sat4    | I <sub>O</sub> = -0.8A, source                              |         | 1.8 | 2.0  | V    |
| Output leakage current        | I <sub>O</sub> 1(leak) | $V_{O} = V_{BB}$ , sink                                     |         |     | 50   | μA   |
|                               | I <sub>O</sub> 2(leak) | $V_{O} = 0V$ , source                                       | -50     |     |      | μΑ   |
| Output sustain voltage        | V <sub>SUS</sub>       | L = 3.9mH, $I_{O}$ = 1.0A, Design guarantee value *         | 30      |     |      | V    |
| Logic Block                   |                        |   |         |     |      |      |
| Logic supply current          | I <sub>CC</sub> ON     | I <sub>1</sub> = 0.8V, I <sub>2</sub> = 0.8V, ENABLE = 0.8V | 50      | 70  | 92   | mA   |
|                               | I <sub>CC</sub> OFF    | ENABLE = 3.2V   | 7       | 10  | 13   | mA   |
| Input voltage                 | VIH                    |   | 3.2     |     |      | V    |
|                               | VIL                    |   |         |     | 0.8  | V    |
| Input current                 | IIH                    | V <sub>IH</sub> = 3.2V                                      | 35      | 50  | 65   | μΑ   |
|                               | ۱ <sub>IL</sub>        | V <sub>IL</sub> = 0.8V                                      | 7       | 10  | 13   | μA   |
| Set current control threshold | Vref/Vsen              | $I_1 = 0.8V, I_2 = 0.8V$                                    | 9.5     | 10  | 10.5 |      |
| value                         |                        | $I_1 = 3.2V, I_2 = 0.8V$                                    | 13.5    | 15  | 16.5 |      |
|                               |                        | I <sub>1</sub> = 0.8V, I <sub>2</sub> = 3.2V                | 25.5    | 30  | 34.5 |      |
| Reference current             | Iref                   | Vref = 5.0V, I <sub>1</sub> = 0.8V, I <sub>2</sub> = 0.8V   | 17.5    | 25  | 32.5 | μA   |
| CR pin current                | ICR                    | CR = 1.0V   | -1.0    |     |      | mA   |
| Thermal shutdown temperature  | T-TSD                  | Design guarantee value *                                    |         | 170 |      | °C   |
| Temperature hysteresis width  | Ts hys                 |   |         | 40  |      | °C   |

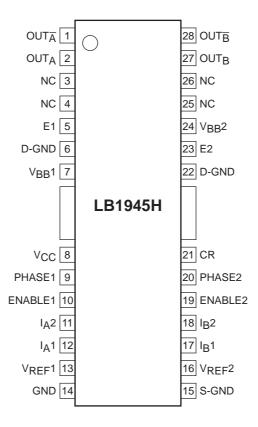
\* Design guarantee value, Do not measurement.

## **Package Dimensions**

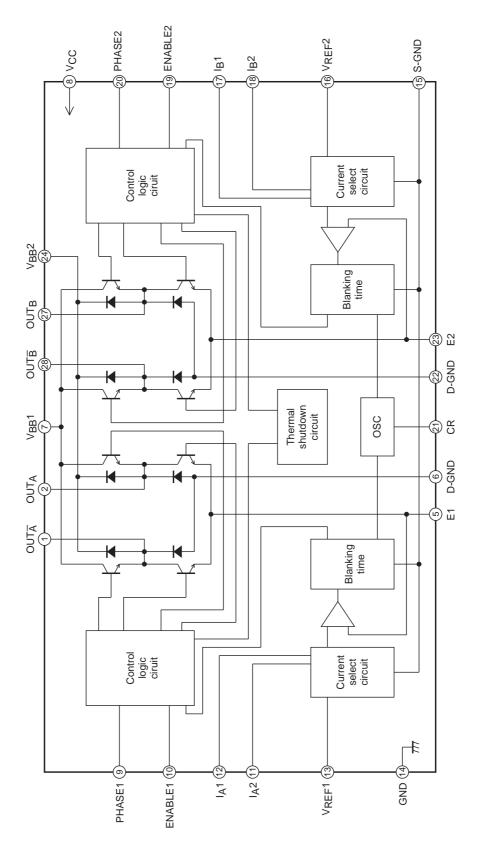
unit : mm (typ) 3233B



# **Pin Assignment**



**Block Diagram** 



# Truth Table

| ENABLE | PHASE | OUTA | OUTA |
|--------|-------|------|------|
| L      | Н     | Н    | L    |
| L      | L     | L    | Н    |
| Н      | -     | OFF  | OFF  |

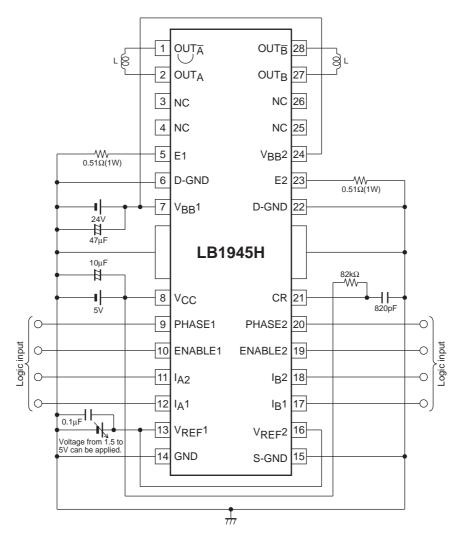
| I <sub>1</sub> | I <sub>2</sub> | Output current                             |
|----------------|----------------|--|
| L              | L              | Vref / (10 $\times$ RE) = I <sub>OUT</sub> |
| Н              | L              | Vref / (15 × RE) = $I_{OUT} \times 2/3$    |
| L              | Н              | Vref / (30 × RE) = $I_{OUT} \times 1/3$    |
| Н              | Н              | 0  |

Note: Output is OFF when ENABLE = H or when  $I_1 = I_2 = H$ .

## **Pin Function**

| Pin No. | Pin name                          | Function   |
|---------|-----------------------------------|--|
| 7       | V <sub>BB</sub> 1                 | Output stage power supply voltage pin.                                   |
| 24      | V <sub>BB</sub> 2                 | Cathode pin for the upper-side diodes.                                   |
| 5       | E1                                | Insert resistor RE between these pins and ground to control set current. |
| 23      | E2                                |  |
| 2       | OUTA                              | Output pins.   |
| 1       | OUTA                              |  |
| 27      | OUTB                              |  |
| 28      | OUTB                              |  |
| 14      | GND                               | Ground pin.  |
| 15      | S-GND                             | Sense ground pin.  |
| 6       | D-GND                             | Lower-side internal diode ground (anode).                                |
| 22      | D-GND                             |  |
| 21      | CR                                | Triangular wave chopping with CR constant setting.                       |
|         |                                   | Triangular wave OFF time is noise cancel time.                           |
| 13      | V <sub>REF</sub> 1                | Output current setting pins.   |
| 16      | V <sub>REF</sub> 2                | (Output current is set by inputting a 1.5V to 7.5V voltage.)             |
| 9       | PHASE1                            | Output phase select input pin.   |
| 20      | PHASE2                            | High input: $OUT_A = H$ , $OUT_A = L$                                    |
|         |                                   | Low input: $OUT_A = L$ , $OUT_{\overline{A}} = H$                        |
| 10      | ENABLE1                           | Output ON/OFF setting input pins.  |
| 19      | ENABLE2                           | High input: output OFF   |
|         |                                   | Low input: output ON   |
| 12,11   | I <sub>A</sub> 1,I <sub>A</sub> 2 | Output current setting digital input pins.                               |
| 17,18   | I <sub>B</sub> 1,I <sub>B</sub> 2 | Current is set to 1/3, 2/3, 1 by High and Low combinations.              |
| 8       | V <sub>CC</sub>                   | Logic block power supply voltage pin.                                    |

# **Application Circuit Example**



The fin on the bottom of HSOP-28H package and the fins between pins 7 and 8 and 21 and 22 should be grounded.

## **Usage Notes**

#### 1. VREF pin

Because the VREF pin is used as reference voltage input pin for the current setting, care must be taken to prevent noise from affecting the input.

#### 2. GND pin

Because this IC switches large currents, the ground pattern must be designed with care. The fin on the bottom of the package and the fins between pins 7 and 8 and 21 and 22 should be grounded. Low-impedance patterns should be used in blocks where large currents flow, and these blocks should be separated from low-level signal blocks. In particular, the ground of the sense resistor RE at pin E should be located close to the IC ground. Pattern layout should be designed so that the capacitors between  $V_{CC}$  and ground and  $V_{BB}$  and ground are close to  $V_{CC}$  and  $V_{BB}$ .

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